

Localization internship

Possible projects:

- Lidar-based localization using LeGO-LOAM or similar approach.
- Camera-based localization for using ORB-SLAM or similar approach.

Links:

- <https://github.com/RobustFieldAutonomyLab/LeGO-LOAM>
- <https://github.com/TixiaoShan/LIO-SAM>
- https://github.com/UZ-SLAMLab/ORB_SLAM3
- https://github.com/raulmur/ORB_SLAM2

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